

```
1 //
2 // Created by Cameron Dietz on 10/8/18.
3 //
4 #include <iostream>
5 #include <vector>
6 #include <cstdlib>
7 #include <cmath>
8 #include <chrono>
9 #include <fstream>
10 #include <iomanip>
11 #include <string>
12
13 using namespace std;
14
15 int colorPath(const vector<vector<int>>& heightMap, vector<vector<int>>& r, vector<vector<int>>& g, vector<vector<int>>& b, int color_r, int color_g, int color_b, int start_row, int start_col = 0);
16
17 int main() {
18     //initialize all variables
19     int a=0;
20     int row;
21     int col;
22     int minval;
23     int maxval;
24     int x;
25     double val;
26     double grey;
27     std::string fileName;
28
29     int bestDist = 10000000;
30     int dist = 0;
31     int bestpath = 0;
32
33     //initialize vectors
34     std::vector<int> v;
35     std::vector<std::vector<int>> > dat;
36
37     //recieve user input
38     std::cout << "Enter number of rows: ";
39     std::cin >> row;
40     std::cout << "Enter number of columns: ";
41     std::cin >> col;
42     std::cout << "Enter name of file: ";
43     std::cin >> fileName;
44     std::string outFileFileName = fileName+".ppm";
45
46     //call the file to recieve data
47     std::ifstream ifile(fileName.c_str());
```

```
48
49 //check to see if the file can be opened
50 if(!ifile.is_open())
51 {
52     std::cout << "Error: Could not access file." <<endl;
53     return -1;
54 }
55
56 //creates the output file
57 std::ofstream ofile(outFileName.c_str());
58
59 //checks to see if the output file can be accessed
60 if(!ofile.is_open())
61 {
62     std::cout << "Error: Could not access output file." <<endl;
63     return -1;
64 }
65
66 //find max and min values
67 while(ifile >> x){
68
69     if(a==0){
70         minval=x;
71         maxval=x;
72         a++;
73     }
74     if(x < minval){
75         minval = x;
76     }
77     if(x > maxval){
78         maxval = x;
79     }
80
81     v.push_back(x);           //puts the values into the vector v in
                              appropriate number of columns
82     if(v.size() == row)
83     {
84         dat.push_back(v);    //adds that vector to the dat
                              vector
85         v.clear();
86     }
87 }
88
89 //checks to see if the end vector matrix is the appropriate size
90 if(v.size()!=0&&dat.size()!=col)
91 {
92     std::cout << "Error: Recieved more or less data values than
                              expected." <<endl;
93     return -1;
```

```
94     }
95     //initializes vectors within a vector one for each row and main one is ↗
        set to the number of columns
96     std::vector<std::vector<int> > r(col);
97     std::vector<std::vector<int> > b(col);
98     std::vector<std::vector<int> > g(col);
99
100    //goes through each value in the vector matrix and adds the calculated ↗
        grey scale rgb value to the vector rgb
101    for(int i=0;i<dat.size();i++){
102        for(int j=0;j<dat.at(i).size();j++){
103            if(minval==maxval){
104                val=0;
105            }else{
106
107                val=round(((dat.at(i).at(j) - minval)*255.0)/(maxval - ↗
                    minval));
108            }
109            grey=val;
110            r.at(i).push_back((int)grey);
111            b.at(i).push_back((int)grey);
112            g.at(i).push_back((int)grey);
113        }
114    }
115
116
117    for(int i=0;i<dat.size();i++){
118
119        dist = colorPath(dat,r,g,b,252,25,63,i);
120
121        if(dist<bestDist){
122            bestDist = dist;
123            bestpath = i;
124
125        }
126    }
127
128 }
129
130 dist = colorPath(dat,r,g,b,31,253,13,bestpath);
131
132 //inputs the first statements into the ppm file and then adds the ↗
        three of the rgb value from the vector into the file
133 ofile<<"P3"<<endl;
134 ofile<<col<<" "<<row<<endl;
135 ofile<<255<<endl;
136
137 for(int i=0;i<dat.size();i++){
138     for(int j=0;j<dat.at(i).size();j++){
```

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139         ofile<<r.at(i).at(j)<<" "<<g.at(i).at(j)<<" "<<b.at(i).at(j)  ↗
           <<" ";
140     }
141     ofile <<endl;
142 }
143 }
144
145 // Output distance
146 int colorPath(const vector<vector<int>>& heightMap, vector<vector<int>>&  ↗
    r,
147     vector<vector<int>>& g, vector<vector<int>>& b, int color_r, int  ↗
    color_g,
148     int color_b, int start_row, int start_col) {
149
150     int j = 0;
151     int i = start_row;
152     int diff0 = 0;
153     int diff1 = 0;
154     int diff2 = 0;
155     int minNum;
156     int distance = 0;
157     r.at(start_row).at(0) = color_r;
158     g.at(start_row).at(0) = color_g;
159     b.at(start_row).at(0) = color_b;
160
161     while (j < heightMap[0].size() - 1) {
162         if (i <= 0) {
163             diff1 = abs(heightMap.at(0).at(j) - heightMap.at(0).at(j +  ↗
                1));
164             diff2 = abs(heightMap.at(0).at(j) - heightMap.at(1).at(j +  ↗
                1));
165             diff0 = max(diff1, diff2) + 1;
166         }
167         else if (i >= heightMap.size() - 1) {
168             // Check column values of row and row - 1
169             diff0 = abs(heightMap.at(i).at(j) - heightMap.at(i - 1).at(j +  ↗
                1));
170             diff1 = abs(heightMap.at(i).at(j) - heightMap.at(i).at(j +  ↗
                1));
171             diff2 = max(diff0, diff1) + 1;
172         }
173         else {
174             diff0 = abs(heightMap.at(i).at(j) - heightMap.at(i - 1).at(j +  ↗
                1));
175             diff1 = abs(heightMap.at(i).at(j) - heightMap.at(i).at(j +  ↗
                1));
176             diff2 = abs(heightMap.at(i).at(j) - heightMap.at(i + 1).at(j +  ↗
                1));
177         }

```

```
178
179     minNum = min(diff0, min(diff1, diff2));
180
181     if ((minNum == diff0) && (diff0 != diff1) && (diff0 != diff2)) {
182         --i;
183     }
184     else if (((minNum == diff2) && (diff1 != diff2)) || (diff0 ==      ↗
185         diff2 && (diff2 < diff1))) {
186         ++i;
187     }
188
189     distance += minNum;
190     r.at(i).at(j + 1) = color_r;
191     g.at(i).at(j + 1) = color_g;
192     b.at(i).at(j + 1) = color_b;
193     ++j;
194 }
195 return distance;
196 }
197
198
199
200
```